Community Modeling Environment at the Southern California Earthquake Center

Principles, Architecture and Lessons Learned

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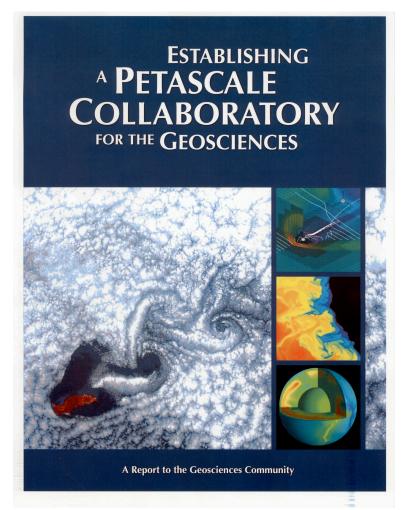


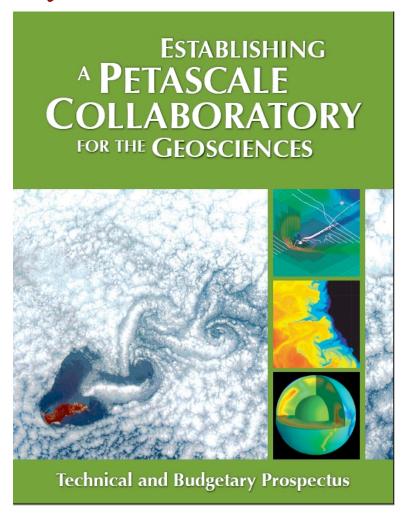






The Geoscientific Community Is Pursuing a Petascale Collaboratory





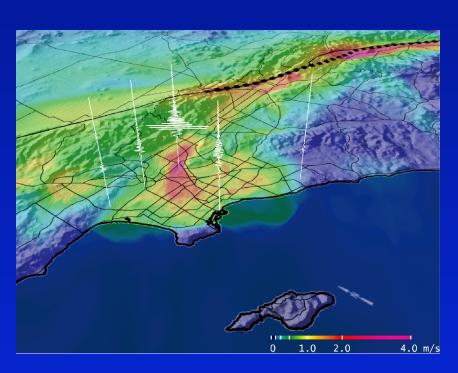
SCEC: An NSF + USGS Research Center

Overview of Talk

- 1. Earthquake System Science and SCEC CME
- SCEC's Earthquake System Science research: Pathways, and Platforms
- 3. Selected aspects that might be adapted to Icesheet Community modeling



SCEC Earthquake System Science – Spanning microseconds to millennia and from microns to 1,000 km









Community Modeling Environment

- SCEC's collaboratory for earthquake system science
- provides the cyberinfrastructure for executing the computational pathways of physics-based seismic hazard analysis (SHA)
- developed and operated by the CME Collaboration
- main facilities are the PetaSHA computational platforms
- Participation by SCEC community is coordinated through a Planning Committee

Geosystems: Defined by Predicted Behavior

- A geosystem comprises a set of interacting elements that changes in time according to a set of prescribed laws, designed to model specific behaviors observed in the Earth environment
- In other words, the behavior defines the system

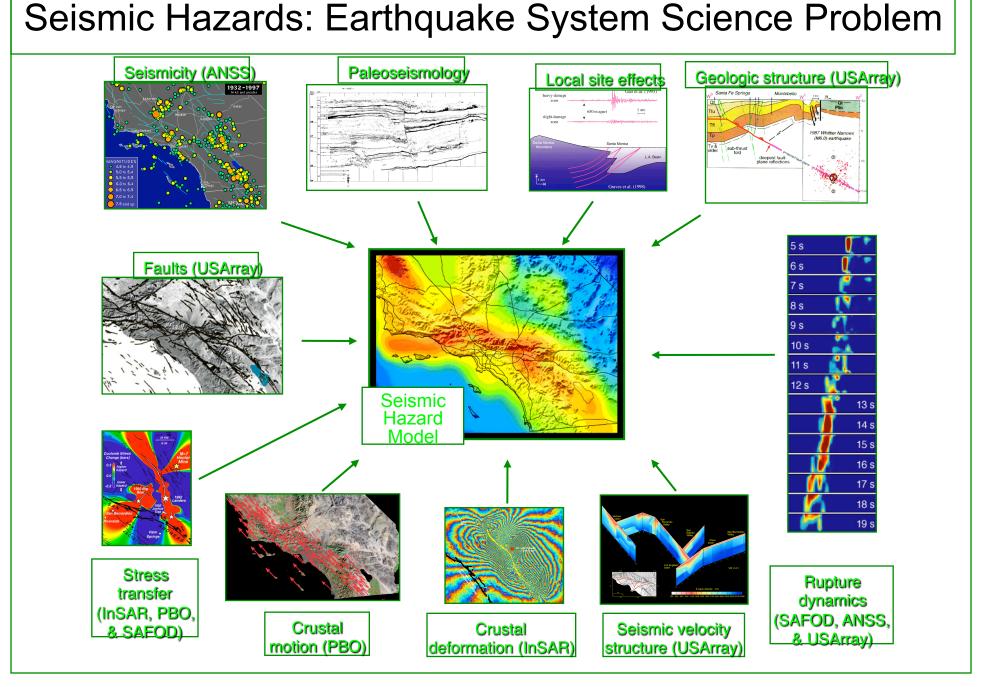
Geosystem

Climate system (a.k.a. "Earth system")
mantle convection
core dynamo
southern polar vortex
orogen
active fault system
super-cell thunderstorm
volcano
petroleum reservoir
ENSO
ICE Sheet

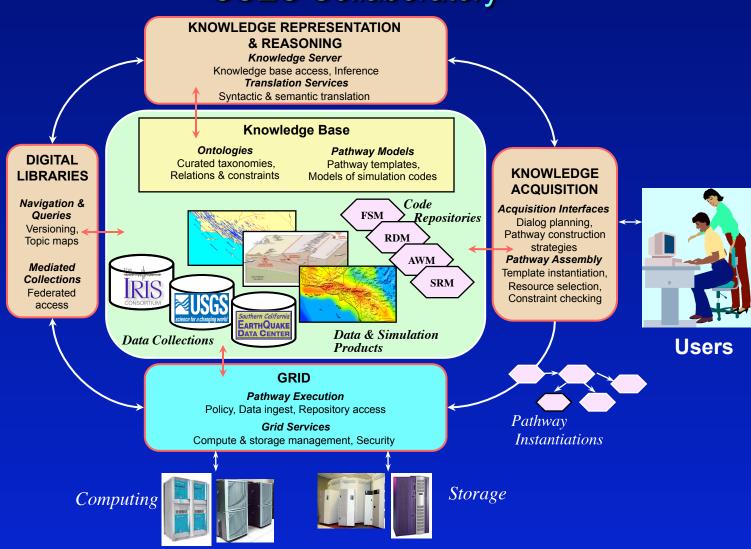
Behavior

climate
plate tectonics
magnetic field
ozone hole
mountain building and erosion
earthquakes
tornado
magmatic eruption
accumulation & flow of petroleum
El Niño
Disintegration? Sea Level change?





SCEC Collaboratory

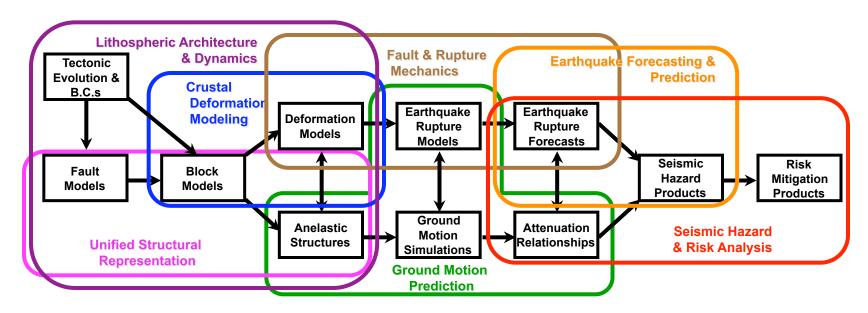


Building a Next-Generation Community Ice Sheet Model LANL, 18-20 August 2008

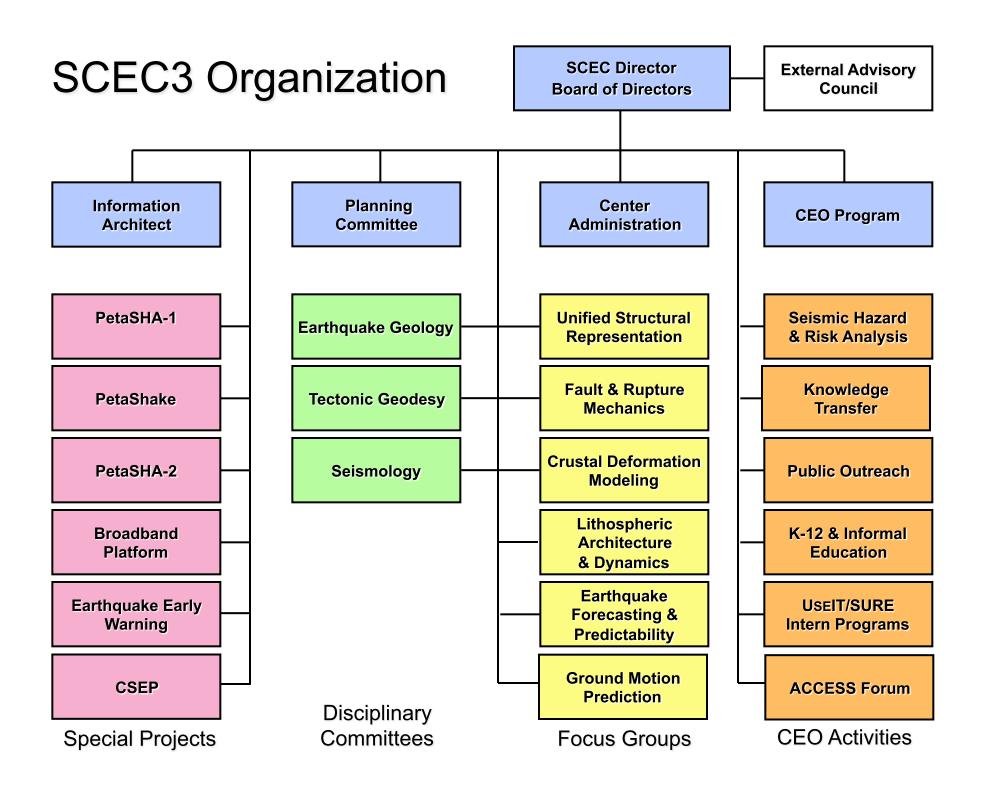


Southern California Earthquake Center

- Involves 500+ scientists at 55 institutions worldwide
- Focuses on earthquake system science using Southern California as a natural laboratory
- Translates basic research into practical products for earthquake risk reduction



SCEC Master Model & Focus Groups



SHA Computational Pathways

Other Data Geology

Geodesy

NSR = Nonlinear Site Response

F3DT = Full 3D Tomography

- 1 Standard seismic hazard analysis
- 2 Ground motion simulation
- 3 Dynamic rupture modeling
- 4 Ground-motion inverse problem

Improvement **Unified Structural Representation** F3DT of models Ground Physics-based **KFR AWP NSR DFR AWP Motions** simulations 3 **Empirical** Intensity **Attenuation** Earthquake Rupture **Measures** models Relationship Forecast

KFR = Kinematic Fault Rupture

DFR = Dynamic Fault Rupture

AWP = Anelastic Wave Propagation

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Types of SCEC Predictive Simulations In Time Scale Order (shortest time scale to longest time scale)

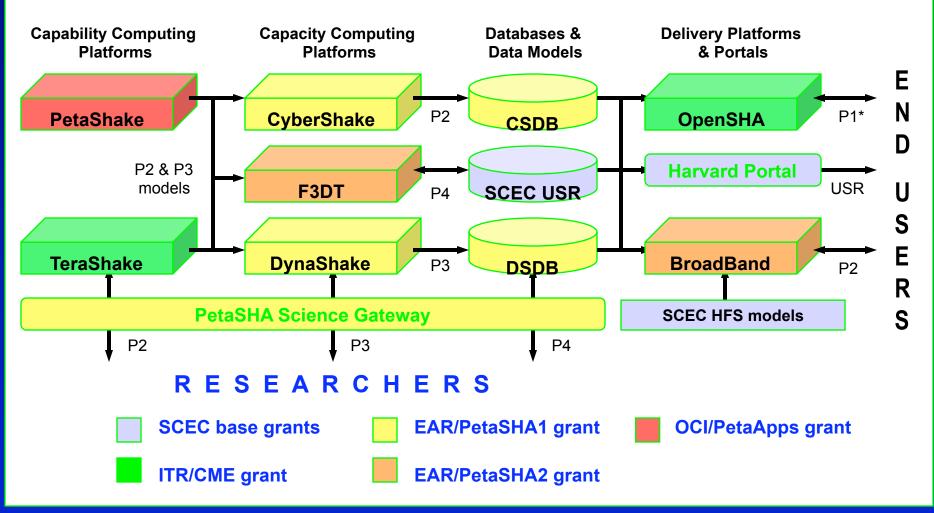
- 1. Dynamic Rupture Simulations
- 2. Large Wave Propagation Simulations
- 3. Earthquake Early Warning
- 4. Ensemble Probabilistic Simulations
- 5. Earthquake Predictions

Common Computing requirements:

- High performance/high throughput computing
- Verification/Validation
- Visualization
- Data Management
- Scientific Workflows

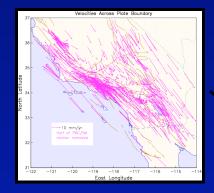
SCEC: An NSF + USGS Research Center

PetaSHA Computational Platforms

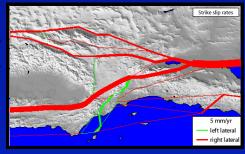


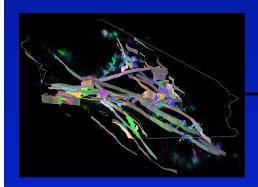
Unified Structural Representation

Crustal Motion Map

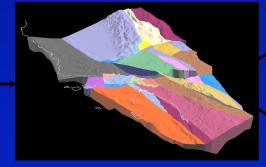


Tectonic models

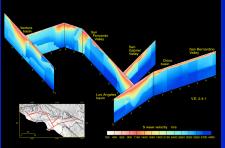




Community Fault Model



Community Block Model



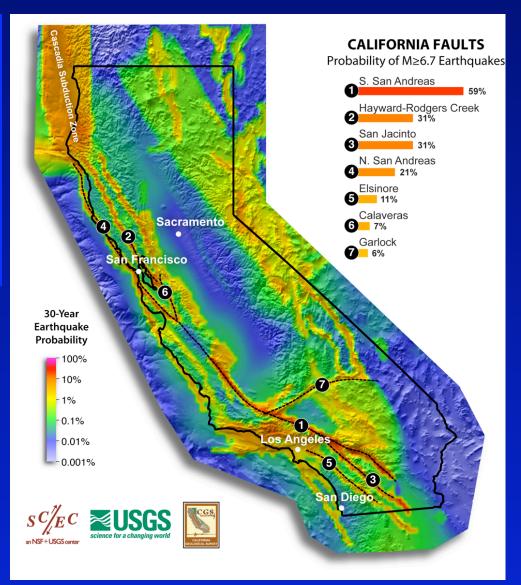
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Structural models

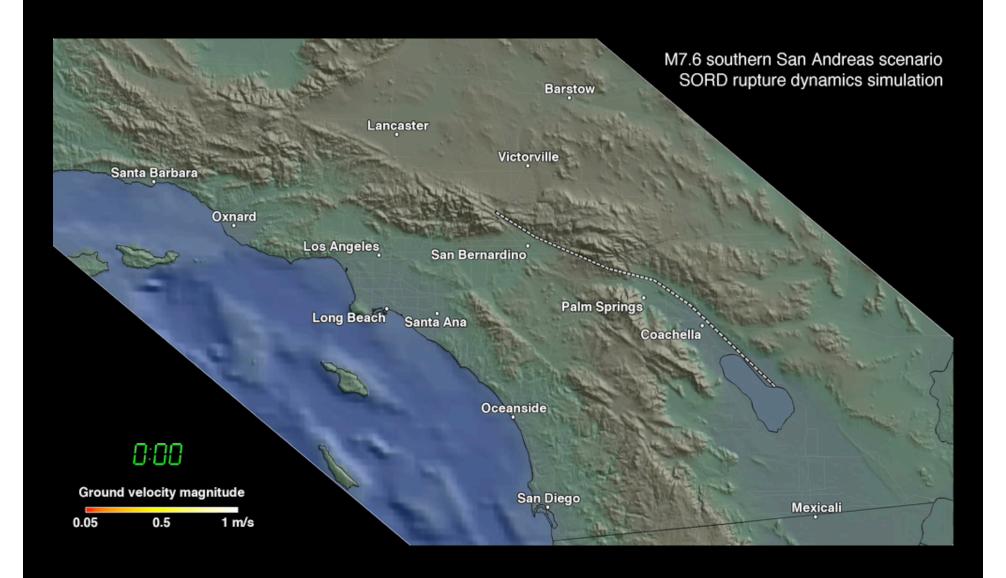
SORD: Support Operator Rupture Dynamics

- Non-planar spontaneous shear crack propagation within a 3D viscoelastic medium.
- Generalized finite difference method of "Support Operators."
- Logically rectangular hexahedral mesh.
- Absorbing boundary zones with perfectly match layers (PML).
- Parallelized for multiprocessor execution with Message Passing Interface (MPI).

Uniform California
Earthquake Rupture
Forecast (UCERF)

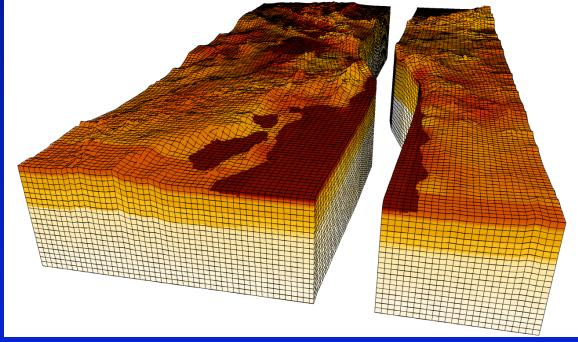


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M_w7.6 Southern San Andreas Simulation

- 600 x 300 x 80 km region, 200 m resolution: 1.8 billion elements.
- 200 x 16 km non-planar spontaneous rupture with stress drop inverted from the M7.3 1992 Landers strong motion records.
- Free surface topography and bathymetry.
- SCEC-CVM 4.0 velocity model.
- 0-0.25 Hz bandwidth.
- 3 min duration.



Equations of Motion

Viscoelastic Solid (Kelvin-Voigt Model)

$$\ddot{\mathbf{u}} = rac{1}{
ho} oldsymbol{
abla} \cdot oldsymbol{\sigma}$$

$$\mathbf{g} = \mathbf{\nabla}(\mathbf{u} + \gamma \dot{\mathbf{u}})$$

$$\sigma = \lambda \operatorname{trace}(\mathbf{g}) + \mu(\mathbf{g} + \mathbf{g}^{\mathrm{T}})$$

 ρ density

 λ, μ elastic moduli

 γ viscosity

u displacement

 σ stress tensor

Free surface boundary condition

$$\tau = \boldsymbol{\sigma} \cdot \hat{\mathbf{n}} = 0$$

Spontaneous Rupture Boundary Condition

$$s = u^+ - u^-$$

$$\boldsymbol{ au}_n = \mathbf{\hat{n}} \cdot \boldsymbol{\sigma} \cdot \mathbf{\hat{n}}$$

$$oldsymbol{ au}_s = (\mathbf{I} - \mathbf{\hat{n}}\mathbf{\hat{n}}) \cdot oldsymbol{\sigma} \cdot \mathbf{\hat{n}}$$

$$|\boldsymbol{\tau}_s| \leq \tau_c$$

$$au_c \dot{\mathbf{s}} = |\dot{\mathbf{s}}| oldsymbol{ au}_s$$

s slip

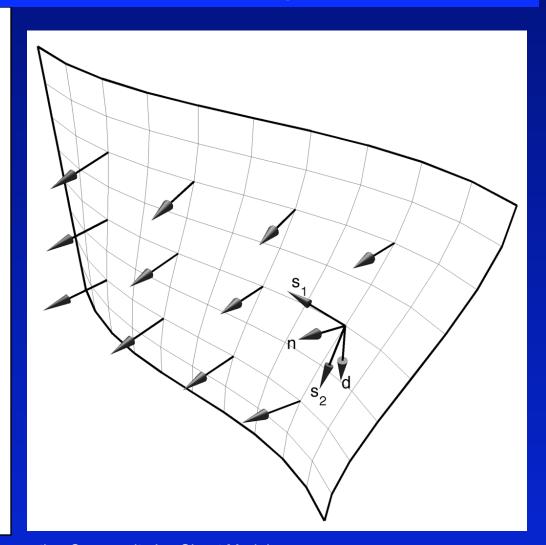
 σ stress tensor

 τ_n normal traction

 au_s shear traction

 au_c frictional strength

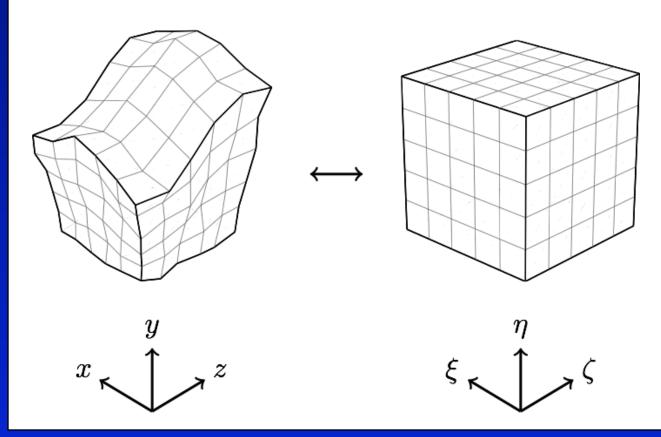
n surface unit normal



Support Operator Numerical Scheme

Derivation:

$$f(oldsymbol{\xi}) = \sum_{lpha,eta,\gamma=0}^n N_{lphaeta\gamma}(oldsymbol{\xi}) f_{lphaeta\gamma} \qquad oldsymbol{
abla} f = rac{\partial f}{\partial oldsymbol{\xi}} \cdot \mathbf{J}^{-1}$$



Support Operator Numerical Scheme

Discrete gradient operator

$$(\mathrm{D}_i f)_{jkl} pprox rac{1}{V_{jkl}} \int_{V_{jkl}} \partial_i f \, dV$$

Continuous divergence theorem

$$\int_{V} f(\mathbf{\nabla} \cdot \mathbf{w}) \, dV + \int_{V} \mathbf{w} \cdot (\mathbf{\nabla} f) \, dV = \int_{S} f \mathbf{w} \cdot d\mathbf{S} = 0$$

Discretized divergence theorem gives the negative adjoint divergence operator

$$\sum_{j,k,l=1}^{m,n,p} f_{jkl}(\mathcal{D}_i w_i)_{jkl} = -\sum_{j,k,l=1}^{m-1,n-1,p-1} (\mathrm{D}_i f)_{jkl}(w_i)_{jkl}$$

...and conservation of energy is obeyed.

CMU Hercules platform

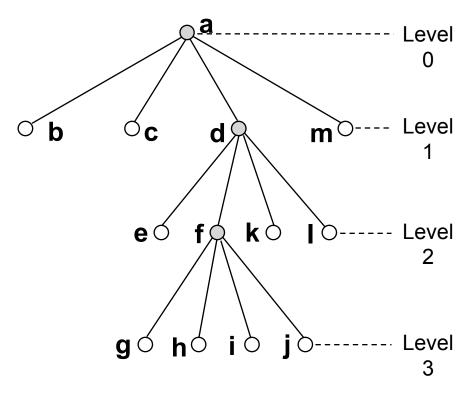
Finite element approach
Structured, variable mesh
Oct-tree management of model and simulations

Equivalent Octree Representations

Domain Representation

У 15 14 k 13 12 m 11 10 9 g h 8 7 6 5 4 b 3 2 1 9 10 11 12 13 14 15 Χ

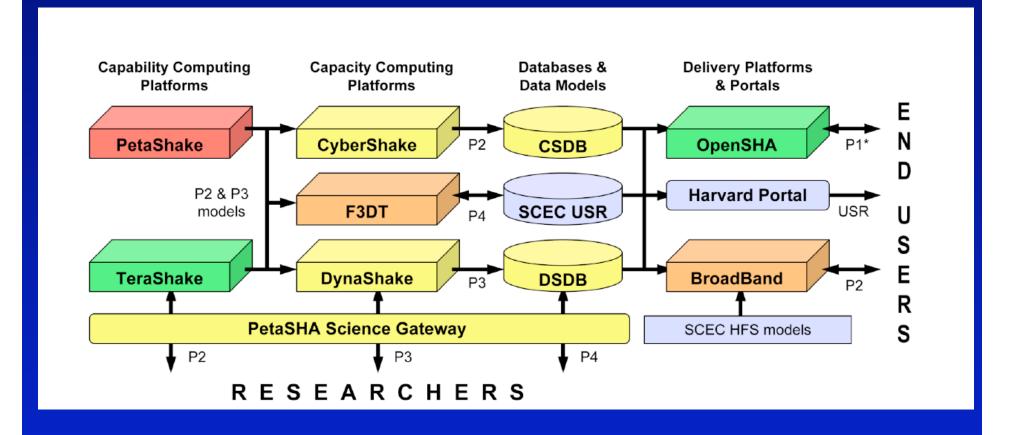
Tree Representation



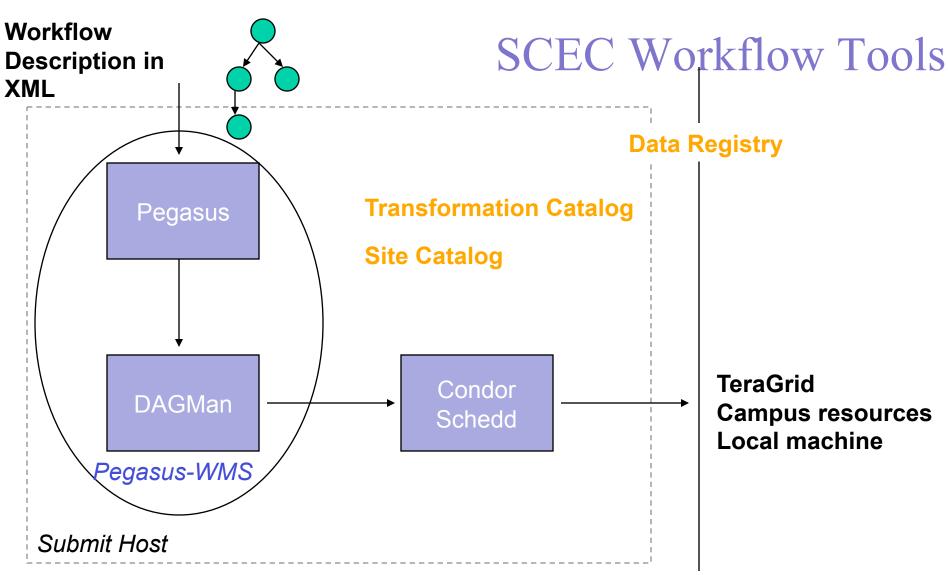
- : Interior octant : Leaf octant

Hercules System - David R. O'Hallaron

SCEC Computational Platforms

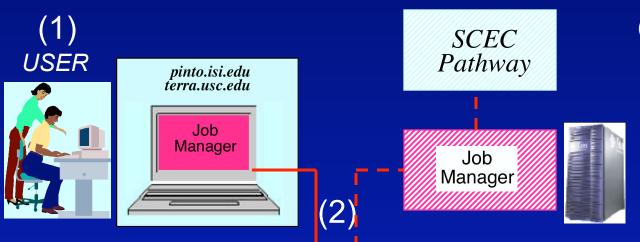






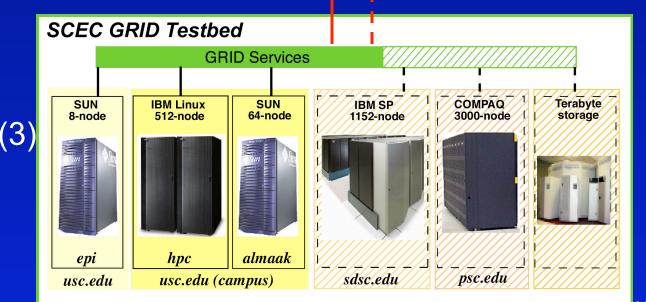
Pegasus restructures and optimizes the workflow, provides reliability
Pegasus-WMS is a collaboration with UW Madison and funded by NSF under SDCI

SCEC Computational Grid Testbed



(1) Scientist issues a request (compute or data retrieval) to "Job Manager"

Future complex pathways require a more versatile Job Manager.



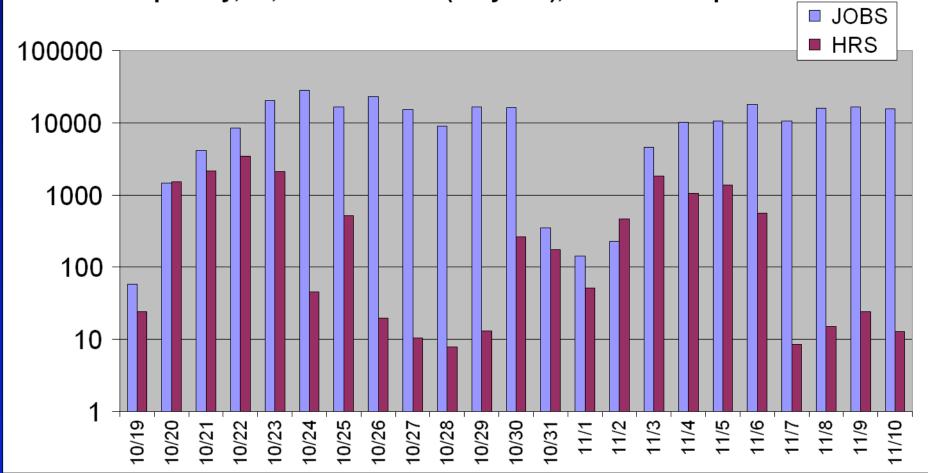
- (2) Job Manager talks to a Testbed computer via GRID service communication protocals.
- (3) Testbed computer performs the requested actions.

Model اعد



Were we were: Executions on the TG Fall 2005 (Pasadena and USC)

Number of jobs per day (23 days), 261,823 jobs total, Number of CPU hours per day, 15,706 hours total (1.8 years), 20TB of data processed



Managing Large-Scale Workflow Execution from Resource Provisioning to Provenance tracking: The CyberShake Example, Ewa Deelman, et al, e-Science 2006, Amsterdam, December 4-6, 2006, best paper award

Code comparisons

2002 SCEC Annual Meeting

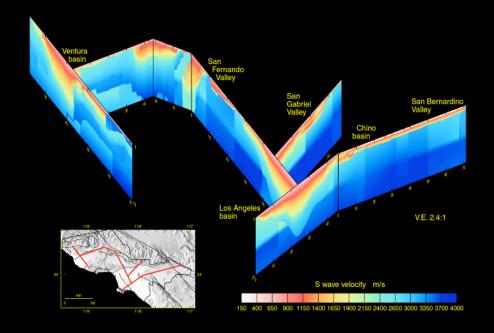
PEER/SCEC Collaboration for Validation of 3D Wave Propagation Codes

Steven Day
San Diego State University

September 10, 2002

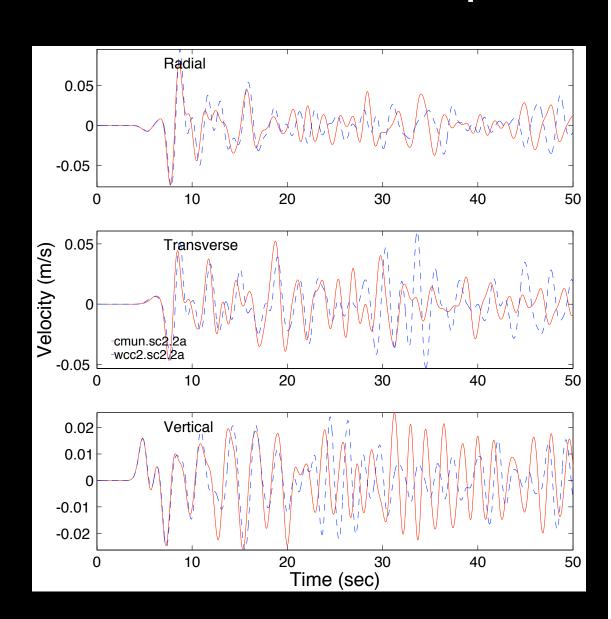
Stage II: Complex Structure (perfectly elastic)

- SCEC 3D Reference Model for So. California
- Modified for minimum S velocity of 500 m/s
- Point dislocation source
- Target bandwidth 0 0.5 Hz



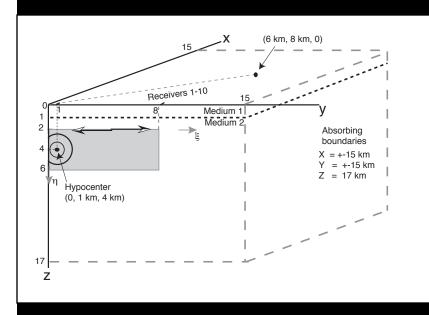
SCEC Reference Model Example

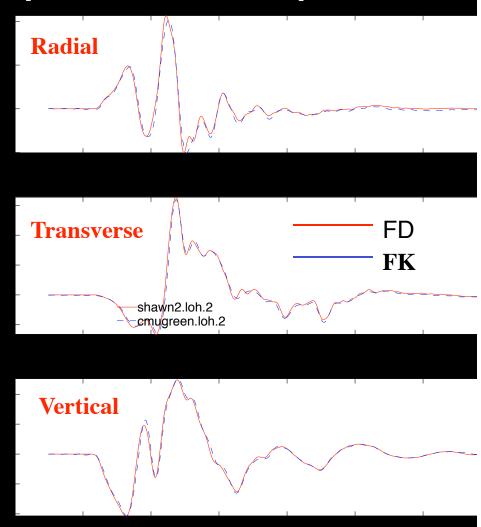
- Site in San Fernando Valley
- Point dislocation source in Northridge aftershock zone
- Very fine FE meshing of shallow sediments provides best reference solution (shown in red)
- Compared here with FD (blue)



Propagating Rupture Example

Low-velocity elastic layer Propagating dislocation





Stage III

Anelastic Attenuation

No-memory methods (narrow absorption band)

- Maxwell solid
- Voigt Solid

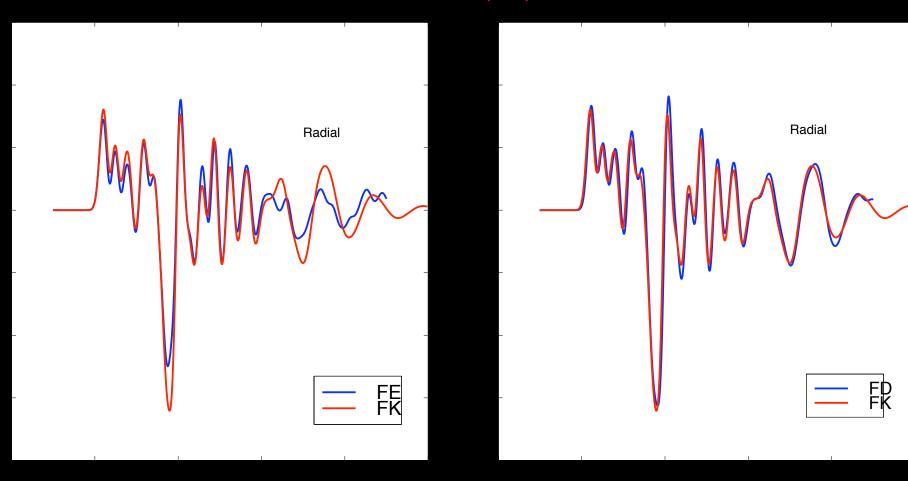
Memory variable methods (broad absorption band)

- Conventional (anelastic relaxations on unit cell) √
- Coarse (anelastic relaxations on larger unit cell) √

No-memory-variable formulation (Maxwell)

Coarse memory-variable Formulation (8 relaxations)

Reference Solution (FK) in red



END